

DIFFERENCE SCHEME for SEMILINEAR REACTION-DIFFUZION PROBLEM of ELIPTIC TYPE

Dr.sci Enes Duvnjaković,
Dr.sci Nermin Okičić
Faculty of Natural Sciences, Mathematics Department, Tuzla,
Bosnia and Herzegovina

ABSTRACT

In this paper we consider semilinear elliptic Dirichlet's boundary value problem with small parameter, well known as singularly perturbed semilinear reaction-diffusion problem. Using theory of projection-mesh methods, precisely using the Galerkin method with natural choice of test function, the given boundary problem is discretized and we get a discrete analog non-linear system. Solving the non-linear difference scheme, we come to the approximate solution of the problem.

Keywords: semi-linear elliptic problem, difference scheme, semi-linear reaction-diffusion problem

1. INTRODUCTION

In rectangular domain $\Omega = \{(x, y) \in R^2 : 0 < x < l_1, 0 < y < l_2\}$,

consider semilinear elliptic equation

$$\varepsilon^2 \Delta u(x, y) = F(x, y; u) \quad (\varepsilon \in (0, 1]) \quad (1)$$

where $F(x, y; u)$ is sufficiently regular function, which has strictly positive partial derivative with respect to u ,

$$F_u = \frac{\partial F(x, y; u)}{\partial u} \geq m > 0 \quad (m = \text{const.}) \quad (2)$$

Propose Dirichlet's boundary condition : $u(x, y)|_G = 0$, (G bound area Ω).

(3)

We call problem (1) – (3) semilinear elliptic Dirichlet's boundary problem. Estimate solution of this problem is given in [3]. Notice that analog one-dimensional problem is considered in [2] and will be basic start point for discretization of problem (1) – (3). The aim of mentioned discretization is getting difference scheme which will, uniformly converge to exact solution of problem (1)–(3) (in points of our mesh), with respect to perturbed parameter ε .

2. DISCRETIZATION OF THE PROBLEM

Define mesh $\bar{\omega}_h = \bar{\omega}_h^1 \times \bar{\omega}_h^2$, on set $\bar{\Omega}$, where

$$\bar{\omega}_h^1 = \{ x_i : i = 0, 1, \dots, N_1; x_0 = 0, x_{N_1} = l_1 \},$$

$$\bar{\omega}_h^2 = \{ y_j : j = 0, 1, \dots, N_2; y_0 = 0, y_{N_2} = l_2 \}.$$

Let $G_h = \bar{\omega}_h \cap G$ and $\omega_h = \bar{\omega}_h \cap \Omega$. Thus, $\bar{\omega}_h = \omega_h \cup G_h$, where sets in last union are disjoint.

Let $\psi(t, w) = f(t, w) - \gamma w$ ($\gamma = \text{const.} > 0$). Now, we can consider next boundary problem

$$\begin{aligned} L_\varepsilon w &\equiv \varepsilon^2 w''(t) - \gamma w(t) = \psi(t, w) \text{ on } (0, 1) \\ w(0) &= 0 \quad ; \quad w(l) = 0, \end{aligned} \quad (4)$$

on given mesh

$$\{t_i : i = 0, 1, \dots, N; t_0 = 0; t_N = l\}.$$

Using results from [2], we have

$$\begin{aligned} (T_w)_i &= a_i w_{i-1} - c_i w_i + a_{i+1} w_{i+1} = \varepsilon^{-2} \left[\int_{t_{i-1}}^{t_i} u''_{i-1}(s) \psi(s, w) ds + \int_{t_i}^{t_{i+1}} u'_i(s) \psi(s, w) ds \right], \\ i &= 1, 2, \dots, N-1 \quad ; \quad w_0 = w_N = 0, \end{aligned} \quad (5)$$

where

$$w_i = w(t_i) \quad ; \quad a_i = \frac{\beta}{\sinh(\beta \Delta t_{i-1})} \quad ; \quad c_i = \frac{\beta}{\tanh(\beta \Delta t_{i-1})} + \frac{\beta}{\tanh(\beta \Delta t_i)} \quad ; \quad \beta = \frac{\sqrt{\gamma}}{\varepsilon}.$$

If we approximate right side in (5), by replacing function $\psi(t, w(t))$ on $[t_i, t_{i+1}]$ with its value in point t_i , we get next difference scheme

$$a_i \bar{w}_{i-1} - c_i \bar{w}_i + a_{i+1} \bar{w}_{i+1} = \frac{\Delta c_i}{\gamma} \psi(t_i, \bar{w}_i), \text{ where}$$

$$\frac{\Delta c_i}{\gamma} = \frac{1}{\varepsilon^2} \left[\int_{t_{i-1}}^{t_i} u''_{i-1}(s) ds + \int_{t_i}^{t_{i+1}} u'_i(s) ds \right].$$

Above difference scheme can be written as

$$\begin{aligned} (T_h \bar{w})_i &\equiv \frac{\gamma}{\Delta c_i} (a_{i+1} (\bar{w}_{i+1} - \bar{w}_i) - a_i (\bar{w}_i - \bar{w}_{i-1})) = f(t_i, \bar{w}_i) \\ i &= 1, 2, \dots, N-1 \quad ; \quad w_0 = w_N = 0. \end{aligned} \quad (6)$$

On the line $y = y_j$ ($j = 0, 1, \dots, N_2 - 1$), equation (5) becomes

$$\begin{aligned} (T_u^{(j)})_{i,j} &\equiv a_i^{(j)} u_{i-1,j} - c_i^{(j)} u_{i,j} + a_{i+1}^{(j)} u_{i+1,j} = \varepsilon^{-2} \left[\int_{t_{i-1}}^{t_i} u''_{i-1}(s) \psi_j^{(j)}(s) ds + \int_{t_i}^{t_{i+1}} u'_i(s) \psi_j^{(j)}(s) ds \right], \\ i &= 1, 2, \dots, N_1 - 1; \quad u_{0,j} = u_{N_1,j} = 0, \end{aligned} \quad (7)$$

where

$$\psi_j^{(j)}(s) = F(s, y_j; u(s, y_j)) - \gamma_1 u(s, y_j) - \varepsilon^2 \frac{\partial^2 u(s, y_j)}{\partial y^2},$$

$u_{i,j} = u(x_i, y_j)$; $\gamma_1 = \text{const.} > 0$, and $u_i^{(x)}$, $u_i^{(y)}$ are solutions of boundary problems

$$\begin{aligned} \varepsilon^2 \frac{\partial^2 u'_i(x, y_j)}{\partial x^2} - \gamma_1 u'_i(x, y_j) &= 0 \quad ; \quad u_i^{I(x)}(x_i) = 1 \quad ; \quad u_i^{II(x)}(x_{i+1}) = 0, \\ \varepsilon^2 \frac{\partial^2 u''_i(x, y_j)}{\partial x^2} - \gamma_1 u''_i(x, y_j) &= 0 \quad ; \quad u_i^{II(x)}(x_i) = 0 \quad ; \quad u_i^{II(x)}(x_{i+1}) = 1. \end{aligned}$$

Similarly, on the line $x = x_i$ ($i = 0, 1, \dots, N_1 - 1$), equation (5) becomes

$$\begin{aligned} (T_u^{(2)})_{i,j} &= a_j^{(2)} u_{i,j-1} - c_j^{(2)} u_{i,j} + a_{j+1}^{(2)} u_{i,j+1} = \varepsilon^{-2} \left[\int_{y_{j-1}}^{y_j} u_j^{II(y)}(s) \psi_i^{(2)}(s) ds + \int_{y_j}^{y_{j+1}} u_j^{I(y)}(s) \psi_i^{(2)}(s) ds \right], \\ j &= 1, 2, \dots, N_2 - 1; \quad u_{i,0} = u_{i,N_2} = 0, \end{aligned} \quad (8)$$

where $\psi_i^{(2)}(s) = F(x_i, s; u(x_i, s)) - \gamma_2 u(x_i, s) - \varepsilon^2 \frac{\partial^2 u(x_i, s)}{\partial x^2}$,

$\gamma_2 = \text{const.} > 0$, and $u_j^{I(y)}$, $u_j^{II(y)}$ are solutions of boundary problem

$$\begin{aligned} \varepsilon^2 \frac{\partial^2 u'_j(x_i, y)}{\partial y^2} - \gamma_2 u'_j(x_i, y) &= 0 \quad ; \quad u_j^{I(y)}(y_j) = 1 \quad ; \quad u_j^{I(y)}(y_{j+1}) = 0, \\ \varepsilon^2 \frac{\partial^2 u''_j(x_i, y)}{\partial y^2} - \gamma_2 u''_j(x_i, y) &= 0 \quad ; \quad u_j^{II(y)}(y_j) = 0 \quad ; \quad u_j^{II(y)}(y_{j+1}) = 1. \end{aligned}$$

Obviously, we can represent functions $\psi_j^{(1)}(s)$ and $\psi_i^{(2)}(s)$ as

$$\psi_j^{(1)}(s) = \psi_j^{(1)}(x_i) + [\psi_j^{(1)}(s) - \psi_j^{(1)}(x_i)] = \psi_j^{(1)}(x_i) + \int_{y_j}^s d\psi_j^{(1)},$$

$$\psi_i^{(2)}(s) = \psi_i^{(2)}(y_j) + [\psi_i^{(2)}(s) - \psi_i^{(2)}(y_j)] = \psi_i^{(2)}(y_j) + \int_{y_j}^s d\psi_i^{(2)}.$$

Now, equations (7) and (8) can be write as

$$T_h^{(1)} u = F(x, y; u) - \varepsilon^2 \frac{\partial^2 u}{\partial y^2} + Y^{(1)}(x, y; \psi^{(1)}), \quad (9a)$$

$$T_h^{(2)} u = F(x, y; u) - \varepsilon^2 \frac{\partial^2 u}{\partial x^2} + Y^{(2)}(x, y; \psi^{(2)}), \quad (9b)$$

for $(x, y) \in \omega_h$, where

$$Y^{(1)}(x_i, y_j; \psi^{(1)}) = \frac{\gamma_1}{\varepsilon^2 \Delta c_i^{(1)}} \left[\int_{x_{i-1}}^{x_i} u_{i-1}^{II(x)}(s) \left(\int_{x_i}^s d\psi_j^{(1)} \right) ds + \int_{x_i}^{x_{i+1}} u_i^{I(x)}(s) \left(\int_{x_i}^s d\psi_j^{(1)} \right) ds \right],$$

$$Y^{(2)}(x_i, y_j; \psi^{(2)}) = \frac{\gamma_2}{\varepsilon^2 \Delta c_j^{(1)}} \left[\int_{y_{j-1}}^{y_j} u_{j-1}^{II(y)}(s) \left(\int_{y_j}^s d\psi_j^{(2)} \right) ds + \int_{y_j}^{y_{j+1}} u_j^{I(y)}(s) \left(\int_{y_j}^s d\psi_j^{(2)} \right) ds \right].$$

Operators $T_h^{(1)}$ and $T_h^{(2)}$ are defined analogously as in (6). If now, for $(x, y) \in \omega_h$, by adding equations (9a) and (9b), we get

$$T_h^{(1)} + T_h^{(2)} = F(x, y; u) + Y^{(1)} + Y^{(2)} \quad ; \quad (x, y) \in \omega_h; \quad u|_{G_h} = 0. \quad (10)$$

Notice that, in above equation we used the fact that function $u(x, y)$ satisfies equation (1). With $\bar{u}(x, y)$ we denote approximate value of function $u(x, y)$, for $(x, y) \in \omega_h$.

By ignoring of sum $Y^{(1)} + Y^{(2)}$ in equation (10), we get next difference sheme

$$L_h \bar{u} = T_h^{(1)} \bar{u} + T_h^{(2)} \bar{u} = F(x, y; \bar{u}) ; (x, y) \in \omega_h ; \quad u|_{G_h} = 0, \quad (11)$$

or diferently written

$$\begin{aligned} L_h \bar{u}_{i,j} &\equiv \frac{\gamma_1}{\Delta c_i^{(1)}} [a_{i+1}^{(1)}(\bar{u}_{i+1,j} - \bar{u}_{i,j}) - a_i^{(1)}(\bar{u}_{i,j} - \bar{u}_{i-1,j})] + \frac{\gamma_{21}}{\Delta c_j^{(2)}} [a_{j+1}^{(2)}(\bar{u}_{i,j+1} - \bar{u}_{i,j}) - a_j^{(2)}(\bar{u}_{i,j} - \bar{u}_{i,j-1})] = \\ &= F(x_i, y_j; \bar{u}_{i,j}), \quad (i = 1, 2, \dots, N_1 - 1; j = 1, 2, \dots, N_2 - 1), \\ \bar{u}_{0,j} = \bar{u}_{N_1,j} &= 0 \quad (j = 0, 1, \dots, N_2), \quad \bar{u}_{i,0} = \bar{u}_{i,N_2} = 0 \quad (i = 0, 1, \dots, N_1). \end{aligned} \quad (12)$$

Example

Apply this method on solving of Dirichlet's boundary problem

$$\begin{aligned} 0,01 \Delta u(x, y) &= x^2 - y^2, \quad \text{on } D = [-1, 1] \times [-1, 1], \\ u(x, y)|_G &= 0 \quad (G - \text{bound of area } D). \end{aligned} \quad (13)$$

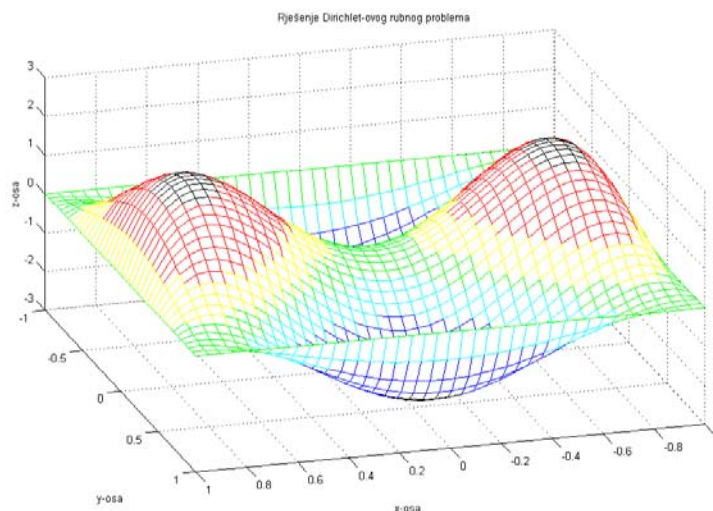


Figure 1. Approximate solution of problem (13)

3. REFERENCES

- [1] M.Stynes, An Adaptive Uniformly Convergent Numerical Method for a Semilinear Singular Perturbation Problem, Siam J. Numer. Anal., v26, pp.442-455, 1989.
- [2] N.Okicic; E.Duvnjakovic, Difference Scheme for Nonlinear Singular Perturbation problem, Zbornik radova PMF 1, pp.53-60, 2004.
- [3] E.Duvnjakovic, Procjena rjesenja kvazilinearnog eliptickog rubnog problema, Zbornik radova PMF 2, pp.54-59, 2005.
- [4] E. Duvnjaković, A Class of Difference schemes for singular perturbation problem, Proceedings of the 7 International Conference on Operational research, Croatian OR Society, pp. 197-208, 1999.
- [5] K. Nijijima, A Uniformly Convergent Difference Scheme for a Semilinear Singular Perturbation Problem, Numer. Math., v 43, pp.175-198, 1984.